

Proportional Directional Control Valve with Digital Control Electronics and Feedback

PRM7-06

Size 06 (D03) • Q_{max} 40 l/min (11 GPM) • p_{max} 350 bar (5100 PSI)



Technical Features

- Direct acting, proportional control valve with integrated on-board digital electronic unit, spool position feedback and process feedback
- Control valve with subplate mounting surface acc. to ISO 4401, DIN 24340 (CETOP 03) standards
- > The valve opening and resulting flow rate can be modulated continuously in proportion to the reference signal
- > Digital converter card allows fine control of the valve spool position, reducing hysteresis and response time and optimizing the performance of the valve
- Various models with or without onboard digital converter card or position sensor feedback available
- > Used for directional and speed control of hydraulic actuators
- > Wide range of interchangeable spools available
- > For versions without integrated digital electronic unit wide range of solenoid electrical terminal versions available
- > The driver directly manages digital settings. It's possible to customize the settings for special applictions using the optional kit
- In the standard version, the valve housing is phosphated and steel parts zinc-coated for 240 h protection acc. to ISO 9227
- > Enhanced surface protection for mobile sector available (ISO 9227, 520 h salt spray)

Functional Description

The proportional directional valve PRM7 consists of a cast iron housing, a special control spool, two centering springs with supporting washers, one or two proportional solenoids, a position sensor or, if need be, of a control box with digital electronics. The measuring system of the position sensor consists of a differential transformer with core and from the evaluating electronic unit realized in hybrid technique.

Models without integrated electronic unit

The electrical connection of the solenoids is realized by a variety of connectors. The position sensor output is connected by the G4W1F connector plug. Both connectors are supplied.

In this case the proportional valve can be used as follows: **S01, S02** with the internal feedback from the spool position sensor.

Models with the integrated electronic unit

The model comprises an electronic control box that is mounted together with the position sensor on either of the solenoids. The connection of the position sensor to the control box is provided by a cable. For models with two solenoids, the solenoid mounted opposite the control box is connected to the control box by a EN 175301-803 connector.

The connection of the supply voltage, control signal, program input and external output of the position sensor is implemented in a 7-pin connector (M23). The connection of the external feedback is provided by a 5-pin connector, which also has three supply voltages +24 V, +10 V and -5 V for an external sensor available.

The solenoid coils, including the control box, can be turned in the range of \pm 90°. The digital control unit enables the proportional valve to be controlled on the basis of data required from two feedback circuits. In this case the proportional valve can be used as follows:

E01 Proportional directional valve

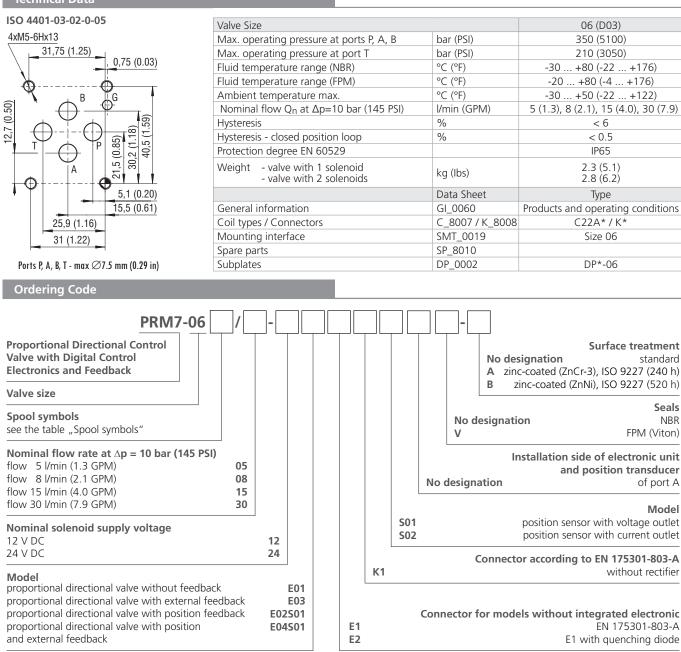
- **E02*S01** Only with the internal feedback from the spool position sensor.
- E03 Only with the external feedback (pressure sensor, position sensor, etc.).
- **E04*S01** With internal and external feedback.

The digital control unit utilizes pulse-with-modulation (PWM) and supplies the solenoids with current proportional to the control signal. The supply current is additionally modulated with a dither frequency. Individual functional parameters are adjusted through software by a special programmer, or by computer through the RS 232 interface. The cable kit must be ordered separately, as detailed on page 4. The correct function of the digital control unit is signaled by a green LED. The incorrect function (failure) is indicated by a red LED. As a standard, the proportional valve is delivered with factory setting.

For a model including an external feedback contact the manufacturer.



Technical Data



- Valves without integrated control electronics with E1, E2 coils (with connector according to EN 175301-803, form A) are delivered in the standard version with connector sockets.

- For proportional valves with two solenoids, one solenoid must be de-energized before the other solenoid can be charged.

- Mounting bolts M5 x 45 DIN 912-10.9 or studs must be ordered separately. Tightening torque is 8.9 Nm (6.56 lbf.ft)

- Besides the shown, commonly used valve versions other special models are available.

- Contact our technical support for their identification, feasibility and operating limits.

Spool Symbols

Туре	Symbol	Туре	Symbol	
2Z51	$a \xrightarrow{A B}_{T T} W$	3Z11		
2Z11	$M \xrightarrow{A \ B}_{T \ T} \xrightarrow{L} b$	3Z12		$\frac{q_A}{q_B} = \frac{1}{2}^*$
2Y51	A B H M	3Y11		
2Y11		3Y12		$\frac{q_A}{q_B} = \frac{1}{2}^*$

*Model for cylinders with asymetric piston area ratio 1:2



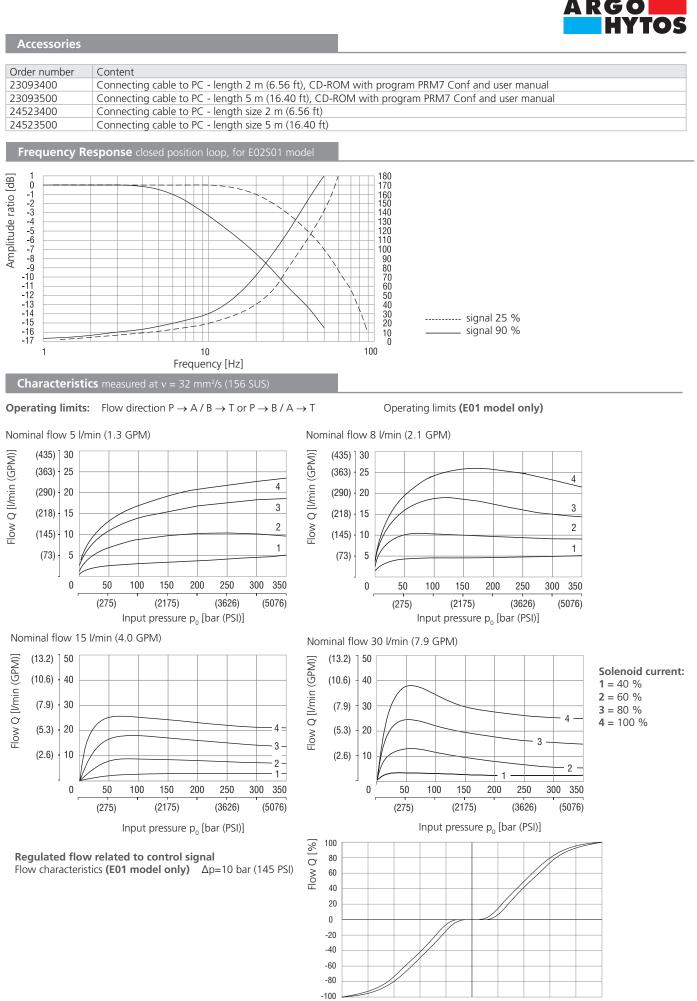
Technical Data of Position Sensor - Voltage Outlet

Operating pressure	bar (PSI)	to 350 (5100), static
Electrical connection * only for S01 model		electrical connector G4W1F Hirschmann*
Contact assigment		1 - Power supply 2 - Command signal 3 - GND 4 - not used
Enclosure protection type according to EN 60529		IP65
Measured distance	mm (in)	8 (0.315)
Operating voltage	V	9.6 30 DC
Linearity error	%	< 1
Current consumption at load current of 2 mA	mA	< 15
Output voltage	V	0 5
Output signal range used: 0 position 1 solenoid - stroke 2.8 mm (0.11 in) 2 solenoids - stroke ± 2.8 mm (0.11 in)	V	2.5 0.75 2.5 0.75 4.025
Max. load current	mA	2
Noise voltage - at load current 0 - at load current of 2 mA	mV _{p-p}	< 20 < 15
Additional output signal error at: - temperature change between 0 80°C (32 176 °F) - between 025 °C (3213 °F) - Load change from 0 to 2 mA		typical 0.2% / 10K max. 0.5 % / 10K max. 0.5 % / 10K 0.1 %
Input voltage change from 9.6 V to 14.4 V from 14.4 V to 30 V	%	< 0.1 < 0.25
Long-term drift (30 days)	%	< 0.25
Cut-off frequency 3dB fall in amplitude Frequency 90°	Hz	> 600 > 600

Technical Data of Position Sensor - Current Outlet

Depending pressure bar (PSI) to 350 (5100), static Electrical connection * only for S01 and S02 model electrical connector G4WIF Hirschmann* Contact assignent 1 - Power supply Contact assignent $3 - G(MD)$ Enclosure protection type according to EN 60529 IP655 Operatin voltage V 20								
Electrical connection * only for S01 and S02 model electrical connector G4W/IF Hirschmann* 1 - Power supply 2 - Command signal 3 - GND 3 - GND Enclosure protection type according to EN 60529 PR65 Departin voltage V Cutput signal range MA Output signal range MA Output signal range MA Dutput signal range MA Output signal range MA Output signal range MA 2 solenoid - stroke 2.8 mm (0.11 in) MA 2 solenoid - stroke 2.8 mm (0.11 in) 4.4 12 2 solenoid - stroke 2.8 mm (0.11 in) 4.4 12 2 solenoid - stroke 2.8 mm (0.11 in) 4.4 12 2 solenoid - stroke 2.8 mm (0.11 in) 4.4 12 2 solenoid - stroke 2.8 mm (0.11 in) 4.4 12 3 colonge from +10 55°C (50 131°F) 3 colonge at impedance Q ≤ 500 Dutput signal ripple mA R.M.S. ≤ 0.02 imit frequency at 3 dB amplitude decrease Hz ≥ 800 Technical Data of Proportional Solenoid Fype of coil V 12 DC 24 DC imit frequency at 20 °C (68 °F) Q 2.3 13.4 Electronics Data 010V, 420 mA,	Linearity		%	<	1			
Contact assignent 1 - Power supply 2 - Command signal 3 - GND 4 - not used Contact assignent 2 - Command signal 3 - GND 4 - not used Inclosure protection type according to EN 60529 PP65 Operatin voltage V Current mA Output signal range mA Output signal range mA Output signal range mA Oposition mA Solenoid - stroke 2.8 mm (0.11 in) Additional output signal error: at temperature change from 50% - at temperature change from 50% - at input voltage change in the range of operating voltage mpedance Dupper Technical Data of Proportional Solenoid Ype of coil V Initing current A Resistance at 20 °C (68 °F) Q Soluply voltage with polarity inversion protection V nput: command signal / according to customer setting nput: command signal / according to customer setting nput: solenoids V <	Operating pressu	re	bar (PSI)	to 350 (51				
Contact assignment 2 - Command Signal 3 - GND 4 - not used Enclosure protection type according to EN 60529 IP65 Operatin voltage V Current mA Current mA Output signal range mA Dutput signal range used: mA Dutput signal error: 12 solenoid - stroke 2.8 mm (0.11 in) 4.4 12. Additional output signal error: 0.2% / 10K at impedance change from +10 55°C (50 131°F) at impedance change in mo 50% at impedance change in mo 50% $\leq 0.05\%$ Duty usignal ripple mA R.M.S. $\leq 0.05\%$ Dutput signal ripple mA R.M.S. ≤ 0.02 Limit frequency at 3 dB amplitude decrease Hz ≥ 800 Technical Data of Proportional Solenoid V 12 DC Supply voltage with polarity inversion protection V 12 L 2 28 VDC (residual ripple < 10%)	Electrical connect	tion * only for S01 and S02 model	electrical connector G4W1F Hirschmann*		G4W1F Hirschmann*			
Operatin voltage V 20	Contact assigmer	nt		1 - Power supply 2 - Command signal 3 - GND				
Operatin voltage V 20	Enclosure protect	ion type according to EN 60529		IP	65			
Dutput signal range mA 4 20 Dutput signal range used: 12 Dutput signal range used: 12 Solenoid - stroke 2.8 mm (0.11 in) 4.4 12 Additional output signal error: 0.2% / 10K at temperature change from +10 55°C (50 131°F) $0.2\% / 10K$ at imput signal error: 0.2% / 10K at imput signal error: 0.2% / 10K at imput signal ringple mA R.M.S. at imput signal ringple mA R.M.S. Solutput signal ring current A Resistance at 20 °C (68 °F) Q Solutput signal ring current A Resistance at 20 °C (68 °F) Q Supply voltage with polarity inversion protection V nput: sconding to customer setting ±10 V, 010 V, ±10 mA, 420 mA, 020 mA, 12 mA±8 mu polition sensor signal solution of the AD converter 010V, ±10 mA, 420 mA, 020 mA Dutput signal ring cervers KHz 12 bit Dutput solenoids 010V, 420 mA, 020 mA	Operatin voltage		V	20	30 DC			
Dutput signal range used: 12 O position 12 Solenoid - stroke 2.8 mm (0.11 in) 4.4 19 6 Additional output signal error: 0.2% / 10K • at temperature change from +10 55°C (50 131°F) 0.2% / 10K • at imput output signal error: 0.2% / 10K • at imput output signal error: 0.2% / 10K • at imput output signal error: 0.2% / 10K • at imput output signal error: 0.1% • at imput outpage change in the range of operating voltage mA R.M.S. mput signal ripple mA R.M.S. • at post output signal error: > 800 Technical Data of Proportional Solenoid V V Initing current R colspan="2">A A Sole of coli V V V V V V V V V V V	Current		mA	<	35			
D position121 solenoid - stroke ±2.8 mm (0.11 in)mA4.4122 solenoid - stroke ±2.8 mm (0.11 in)4.419.6Additional output signal error:0.2% / 10Ka t temperature change from ±10 55°C (50 131°F)0.2% / 10Ka timpedance change in the range of operating voltage0mpedanceQ0.2tput signal ripplemA R.M.S at impedance of the range of operating voltage0 at impedance of the range of operating voltageMA R.M.S at impedance of the range of operating voltage0 at impedance of the range of operating voltageMA R.M.S at impedance of the range of operating voltage≤ 0.02 init frequency at 3 dB amplitude decreaseHztechnical Data of Proportional Solenoidtype of coilVtimiting currentAResistance at 20 °C (68 °F)Q2upt voltage with polarity inversion protectionVnput: scond janal / according to customer setting±10 V, 010 V, ±10 mA, 420 mA, 020 mA, 12 mA±8 mrnput: external feedback signal05 Vnput: external feedback signal020 mAaccording to customer setting12 bitUpturt: solenoidstwo PWM output stages up to max. 3.5 A2WM frequencykHz18action resistance55011 : 1998 class A	Output signal ran	nge	mA	4	. 20			
$\begin{array}{c c c c c c c } \mbox{mark} M & 4.4 12 \\ 3 clenoid - stroke 2.8 mm (0.11 in) & 4.4 19,6 \\ \hline \begin{tabular}{ c c c c c } \mbox{mark} M & 4.4 12 \\ 3 clenoid - stroke 2.8 mm (0.11 in) & 4.4 19,6 \\ \hline \begin{tabular}{ c c c c c c } \mbox{mark} M & 2 & 0.05 \\ \end{tabular} A & 10 & 0.2 \\ \end{tabular} A & 10 \\ \end{tabular} A & 2 \\ \end{tabular} A & 10 \\ \end{tabular} A & 2 \\ \end{tabular} A & 0.05 \\ \end{tabular} A & 0.02 \\ \e$	Output signal rar	nge used:			2			
Additional output signal error: 0.2% / 10K at temperature change from 50% $\leq 0.1\%$ at input voltage change in the range of operating voltage Ω mpedance Ω Output signal ripple mA R.M.S. ining control MA S. Technical Data of Proportional Solenoid MA Fype of coil V 12 DC 24 DC iming current A 2.4 1.0 Resistance at 20 °C (68 °F) Ω 2.3 13.4 Electronics Data Supply voltage with polarity inversion protection V 11.2 28 VDC (residual ripple < 10%)			mA	4.4 .	12			
at impedance change from 50% ≤ 0.1% at input voltage change in the range of operating voltage Ω mpedance Ω Output signal ripple mA R.M.S. imit frequency at 3 dB amplitude decrease Hz Technical Data of Proportional Solenoid Kype of coil V imiting current A Resistance at 20 °C (68 °F) Ω Electronics Data V Supply voltage with polarity inversion protection V nput: spool position sensor signal 05 V nput: spool position sensor signal 010V, 420 mA, 020 mA Nesolution of the A/D converter 12 bit Output: solenoids two PWM output stages up to max. 3.5 A WM frequency KHz 18 Adjustment of parameters µS 170 EMC Interference resistance 55011 : 1998 class A	Additional output	t signal error:		0.2%	/ 10K			
mpedance Ω ≤ 500 Output signal ripple mA R.M.S. ≤ 0.02 imit frequency at 3 dB amplitude decrease Hz ≥ 800 Technical Data of Proportional Solenoid Technical Data of Proportional Solenoid Type of coil V 12 DC 24 DC imiting current A 2.4 1.0 Resistance at 20 °C (68 °F) Ω 2.3 13.4 Electronics Data Electronics Data $\pm 10 V, 010 V, \pm 10 mA, 420 mA, 020 mA, 12 mA±8 m/ supply voltage with polarity inversion protection V \pm 10 V, 010 V, \pm 10 mA, 420 mA, 020 mA, 12 mA±8 m/ nput: spool position sensor signal 010V, 420 mA, 020 mA, 020 mA, 12 mA±8 m/ 010V, 420 mA, 020 mA nput: spool position sensor signal 010V, 420 mA, 020 mA 12 bit Output: solenoids two PWM output stages up to max. 3.5 A PWM frequency KHz 18 Adjustment of parameters \muS 170 EMC Interference resistance 61000 - 6 - 2 : 2005 Radiation resistance 55011 : 1998 class A $	- at imjpedance c	hange from 50%						
Dutput signal ripple mA R.M.S. ≤ 0.02 .imit frequency at 3 dB amplitude decrease Hz ≥ 800 Technical Data of Proportional Solenoid Fype of coil V 12 DC 24 DC .imiting current A 2.4 1.0 Resistance at 20 °C (68 °F) Q 2.3 13.4 Electronics Data Supply voltage with polarity inversion protection V 11.2 28 VDC (residual ripple < 10%)		enange in the range of operating voltage	0	< 1	< 500			
Limit frequency at 3 dB amplitude decreaseHz ≥ 800 Technical Data of Proportional SolenoidType of coilV12 DC24 DCLimiting currentA2.41.0Resistance at 20 °C (68 °F)Q2.313.4Electronics DataSupply voltage with polarity inversion protectionV11.2 28 VDC (residual ripple < 10%)		ple						
Technical Data of Proportional Solenoid Type of coil V 12 DC 24 DC imiting current A 2.4 1.0 Resistance at 20 °C (68 °F) Ω 2.3 13.4 Electronics Data Supply voltage with polarity inversion protection V 11.2 28 VDC (residual ripple < 10%)					— — — — — — — — — — — — — — — — — — — —			
Resistance at 20 °C (68 °F) Ω 2.3 13.4 Electronics Data Supply voltage with polarity inversion protection V 11.2 28 VDC (residual ripple < 10%) nput: command signal / according to customer setting ±10 V, 010 V, ±10 mA, 420 mA, 020 mA, 12 mA±8 m/ nput: spool position sensor signal 05 V nput: external feedback signal 010V, 420 mA, 020 mA Resolution of the A/D converter 12 bit Dutput: solenoids two PWM output stages up to max. 3.5 A PWM frequency kHz 18 Adjustment of parameters µS 170 EMC Interference resistance 61000 - 6 - 2 : 2005	Technical Da	ta of Proportional Solenoid	V	12 DC	24 DC			
Electronics Data Supply voltage with polarity inversion protection Supply voltage with polarity inversion protection V nput: command signal / according to customer setting ±10 V, 010 V, ±10 mA, 420 mA, 020 mA, 12 mA±8 m/ nput: spool position sensor signal 05 V nput: external feedback signal 010V, 420 mA, 020 mA Resolution of the A/D converter 12 bit Output: solenoids two PWM output stages up to max. 3.5 A PWM frequency kHz 18 Adjustment of parameters µS 170 EMC Interference resistance 61000 - 6 - 2 : 2005	Limiting current		A	2.4	1.0			
Supply voltage with polarity inversion protection V 11.2 28 VDC (residual ripple < 10%)	Resistance at 20			2.3	13.4			
nput: command signal / according to customer setting ±10 V, 010 V, ±10 mA, 420 mA, 020 mA, 12 mA±8 m/ nput: spool position sensor signal 05 V nput: external feedback signal 010V, 420 mA, 020 mA Resolution of the A/D converter 010V, 420 mA, 020 mA Output: solenoids two PWM output stages up to max. 3.5 A PWM frequency kHz 18 Adjustment of parmeters µS 170 EMC Interference resistance 61000 - 6 - 2 : 2005	Electronics D	ata						
nput: spool position sensor signal 05 V nput: external feedback signal 010V, 420 mA, 020 mA Resolution of the A/D converter 12 bit Dutput: solenoids two PWM output stages up to max. 3.5 A PWM frequency kHz 18 Adjustment of parameters µS 170 EMC Interference resistance 61000 - 6 - 2 : 2005	Supply voltage w	ith polarity inversion protection	V	11.2 28 VDC (residual ripple < 10%)				
nput: spool position sensor signal 05 V nput: external feedback signal 010V, 420 mA, 020 mA Resolution of the A/D converter 12 bit Dutput: solenoids two PWM output stages up to max. 3.5 A PWM frequency kHz 18 Adjustment of parameters µS 170 EMC Interference resistance 61000 - 6 - 2 : 2005	Input: command	signal / according to customer setting						
nput: external feedback signal 010V, 420 mA, 020 mA Resolution of the A/D converter 12 bit Output: solenoids two PWM output stages up to max. 3.5 A PWM frequency kHz 18 Adjustment of parameters µS 170 EMC Interference resistance 61000 - 6 - 2 : 2005 Radiation resistance 55011 : 1998 class A	Input: spool position sensor signal							
Contraction of all root contention Text Output: solenoids two PWM output stages up to max. 3.5 A PWM frequency kHz Adjustment of parameters µS Interference resistance 61000 - 6 - 2 : 2005 Radiation resistance 55011 : 1998 class A	Input: external feedback signal			010V. 420 m	nA, 020 mA			
Dutput: solenoids two PWM output stages up to max. 3.5 A PWM frequency kHz 18 Adjustment of parmeters µS 170 EMC Interference resistance 61000 - 6 - 2 : 2005 Radiation resistance 55011 : 1998 class A	Resolution of the A/D converter			12 b	uit			
PWM frequency kHz 18 Adjustment of parmeters μS 170 Adjustment of parmeters μS 61000 - 6 - 2 : 2005 EMC Radiation resistance 55011 : 1998 class A				12 0				
Adjustment of parmeters μS 170 EMC Interference resistance 61000 - 6 - 2 : 2005 Radiation resistance 55011 : 1998 class A			kHz	1 5				
MC Interference resistance 61000 - 6 - 2 : 2005 Radiation resistance 55011 : 1998 class A								
MC Radiation resistance 55011 : 1998 class A	, ,		P3		•			
	EMC							
Parameter setting Serial port RS 232 (zero modem). 19200 bauds, 8 data bits, 1 stop bit, no parity. Special software PRM7 Conf.	Paramotor cotting		9 data bits 1 st					





-100

-80 -60 -20

-40

20

40

0

Control signal u_x [%]

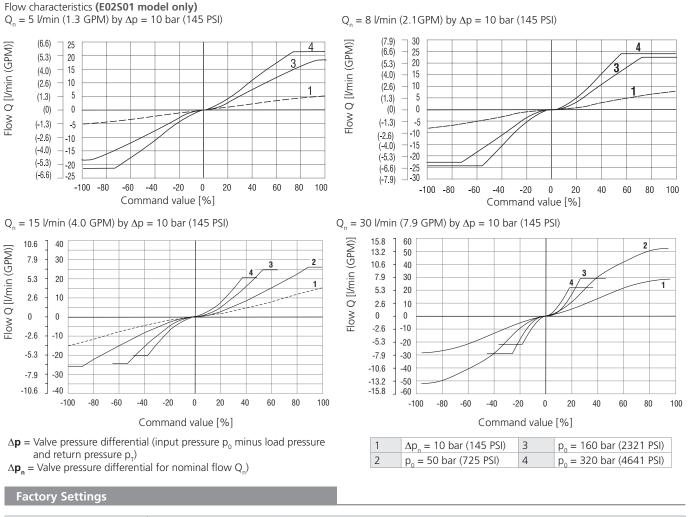
80

60

100

www.argo-hytos.com Subject to change · PRM7-06_5119_4en_11/2018





	Model							
Item	E01		E02S01		E03		E04S01	
	1 Magnet	2 Magnets						
Control signal	0 10 V	± 10 V						
Signal external feedback	-		-	-	0 10 V			
Output position sensor spool	-		0 5 V		-		0 5 V	

Connectors

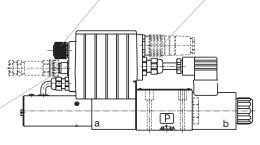
К1	$\overline{\frown}$	
5	7 6	1
	Ó	$\left \left \right _{2} \right $
	3	Ŋ

	cecor rer cype mes (mare)
PIN	Technical data
1	* Power supply input
2	* Ground (power supply)
3	Control signal
4	Ground (signal)
5	Power reference signal
6	Control signal of position sensor spool
7	* Protective earth lead (PE)
*Reco	mmended min. lead cross section 0.75 mm ²
6	
	ector K2 - type M12x1 (male)
PIN	Technical data
1	TxD
2	RxD
3	Ground (signal)
4	Not used
6	
	ector K3 - type M12x1 (female)
PIN	Technical data
1	Power supply output
2	Signal of external feedback
3	Ground
4	Not used
5	Not used

Connector K1 - type M23 (male)

K1 - Main input connector M23 (7 PIN) Cable diameter 8 ...12 mm (0.31...0.47 in).

K2 - Connection RS232 M12x1 (4 PIN) To program the electronics.



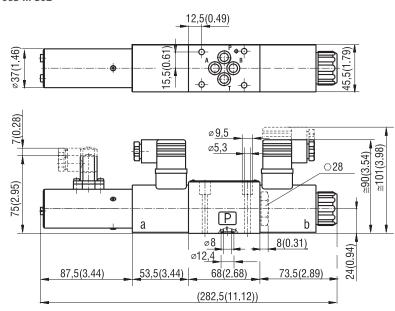
K3 - Conektor M12x1 (5 PIN) External feedback signal (for configurations E03 and E04S01 only).

K2

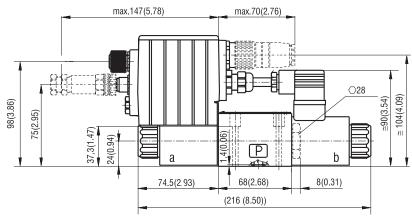
К3

Dimensions in millimeters (inches)

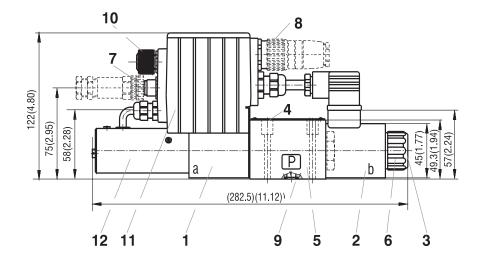
PRM7-063 ... S01 PRM7-063 ... S02











- 1 Solenoid a
- 2 Solenoid b
- 3 Manual override
- 4 Name plate
- 5 4 mounting holes
- 6 Solenoid fixing nut7 Connector M12x1 for connection
- of external feedback
- 8 Main supply connector M23
- **9** Square ring 7.65 x 1.68 (4 pcs.), supplied in delivery packet
- **10** Cover of connector M12x1 for programming
- **11** Plastic box with integrated electronics
- 12 Position sensor